Stochastic Dynamics of Power System

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I. Research Background of SDPS

II. Research on Model of SDPS

III. Research on Analysis of SDPS

IV. Research on Control of SDPS

V. Summary





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Oscillations in Power Systems

> Occurred frequently

1.1 Background

> Unclear mechanism







1.1 Background

Stochastic Disturbances

- Integration of renewable generation
- Integration of new-type load
- > Integration of electronic
 - devices
- Is there any relation?







1.2 Randomness in Power Systems

Types

- Continuous stochastic variable: load, renewable generation, etc.
- Discrete stochastic event: fault location, fault type, network operation, etc.
- Difficulties
 - > Deterministic dynamics: DAE
 - > Stochastic dynamics: DAE + Randomness
- Problems

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> [1 or 0] $\implies P\{\bullet\} \in [1, 0]$



1.3 Research Framework Stochastic Dynamics of Power Systems

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2.1 Introduction to Model of SDPS

- **Topics**
 - > System model
 - Disturbance model
 - Comparisons
 - > Deterministic disturbance Stochastic process
 - > Time domain model Frequency domain model



2.2 Stochastic Model of System



- System Model --- Quasi Hamiltonian
 - Analysis method: Stochastic averaging method
 - > Quasi Hamiltonian System: Stochastic noises excited and dissipated Hamiltonian system

$$\begin{cases} \frac{dQ_i}{dt} = \frac{\partial H}{\partial P_i} \\ \frac{dP_i}{dt} = -\frac{\partial H}{\partial Q_i} - c_{ij}(\boldsymbol{Q}, \boldsymbol{P}) \frac{\partial H}{\partial P_j} + f_{ik}(\boldsymbol{Q}, \boldsymbol{P}) \boldsymbol{\xi}_k(t) + u_i(\boldsymbol{Q}, \boldsymbol{P}) \\ i, j = 1, 2, \cdots n; \ k = 1, 2, \cdots, m \end{cases}$$





2.3 Stochastic Model of Disturbance

Disturbance Model --- Power Spectrum

- > Similarity in the frequency domain
- > Logarithmic linearity









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3.1 Introduction to Analysis of SDPS

Topics

- > Stochastic analysis of stability
- > Stochastic analysis of oscillation
- Stochastic analysis of security

Comparisons

- > Deterministic: stable (1) or unstable (0)
- Stochastic: statistics of stability



3.2 Stochastic Stability



- Theorem of Stochastic Stability
 - In a small-signal stable power system, if the stochastic
 disturbance is bounded, the system satisfies mean stability
 and mean square stability.
 - > This means that there are no new stability issues in power system under small stochastic disturbance.
 - ? Will new oscillation issues happen or not?



3.3 General Forced Oscillation under Small Stochastic Disturbance Input

- Model: linearized system model
- Source: stochastic, not a sine function
- Frequency characteristics: narrow-band, not single-valued

Output

$$S_u(f) \rightarrow \overline{H(f)} \rightarrow S_y(f) = |H(f)|^2 S_u(f)$$

> larger: $S_u(f)$ and $|H(f)|^2$

> 0:
$$S_u(f)$$
 or $|H(f)|^2 = 0$

smaller
$$S_u(f)$$
 or $|H(f)|^2$

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3.3 General Forced Oscillation



Mechanism



- Condition: frequency coverage, not the frequency equivalence
- Possibility: GFO occurs much more frequently than classic forced oscillation



3.3 General Forced Oscillation



GFO in Henan Power Grid

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> Active power of the inter-area UHV tie line



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3.4 General Internal Resonance under Large Stochastic Disturbance

General Forced Oscillation

- Caused by small stochastic disturbance
- > Based on the linear system theory
- > Oscillation modes are completely decoupled

Nonlinear Internal Resonance

- The disturbance is large enough, so the system nonlinearity needs to be considered.
- > Nonlinear interaction exists among the oscillation modes
- Classic internal resonance: single-frequency disturbance
 - General internal resonance: large stochastic disturbance

3.4 General Internal Resonance

Mechanism

> The mode 1 is excited at first, which frequency characteristic is supposed to be narrow-band $\uparrow^{S_k(f)}$

> The input to mode 2 with interaction $S_g(f)$

$$g(z_1) = c_{11}^2 z_1^2$$

> Criterion

$$f_2 \in \left[0, \Delta f\right) \cup \left(2f_1 - \Delta f, 2f_1 + \Delta f\right)$$

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 $-\Delta f$ -

 f_k

 $2\alpha^2 c^2 \Delta f$

 $2f_k$

 $2\Delta f$

0

0

 $4\alpha^2 c^2 \Delta f^2 \delta(f)$

 $-4\alpha^2 c^2 \Delta f$

 Δf

3.4 General Internal Resonance

Case study

- Stochastic disturbance with narrow-band 0.4~0.6Hz
- > Mode 1 is excited at first, according to GFO
- Mode 2 is then excited, although it is not covered



• Internal resonance occurs when the frequency ratio is around 1:2

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3.5 Stochastic Security

Bounded fluctuation region

➤ OMIB – 2 dimension

- to keep the state fluctuation in limits s
- state space trajectory
- rectangle
- > MMS ? dimension
- **How to simplify?**
 - state space



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$R(t \mid \boldsymbol{Y}_0)$ $= P\left\{ Y\left(\tau\right) \in \Omega_{B}, \tau \in \left(0, t\right] \mid Y\left(0\right) = Y_{0} \in \Omega_{B} \right\}$ > The intra-region probability of **BFR-E** - one dimension The Institution of Working to engineer a better world Engineering and Technology

3.5 Stochastic Security

The Intra-region Probability

- The intra-region probability of BFR-O
 - very high dimension

$$R(t \mid H_{0})$$

$$= P\{H(\tau) < \Omega_{E}, \tau \in (0, t] \mid H(0) = H_{0} < \Omega_{E}\}$$
System state
Initial state
BFR
$$\Omega_{E}$$

□ A analytic equation is developed for solving the IRP



 Ω_{p}

3.5 Stochastic Security

La Article Art

Much less consumed time

Case study

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□ Almost the same value



intensity of excitations: a > b > c > d





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4.1 Introduction



Topics

> If the security is not satisfied, control should be put into use

- > Maximizing the security
- Comparisons
 - > Performance index: statistics of the objective function
 - Control law: nonlinearity



4.2 Maximizing the Security



Stochastic model with excitation Control

$$\begin{cases} d\delta_{i} = \omega_{N}\omega_{i}dt \\ d\omega_{i} = \frac{1}{M_{i}} \left[P_{mi} - D_{i}\omega_{i} - G_{ii}E_{qi}^{'2} - E_{qi}^{'}\sum_{j=1, j\neq i}^{n}E_{qj}^{'}B_{ij}\sin\delta_{ij} \right] dt + \frac{\sigma_{i}}{M_{i}}dB_{i}(t) \\ dE_{qi}^{'} = \frac{1}{T_{d0i}^{'}} \left[-b_{i}E_{qi}^{'} + c_{i}\sum_{j=1, j\neq i}^{n}E_{qj}^{'}B_{ij}\cos\delta_{ij} + E_{fdsi} + u_{fi} \right] dt \\ i = 1, 2, ..., n \end{cases}$$





4.2 Maximizing the Security

> Dynamic programming approach

$$\frac{\partial V}{\partial t} = -\sup_{u \in U} \begin{cases} \frac{1}{2} \sigma_{HH}^{2} (H, C_{i}) \frac{\partial^{2} V}{\partial H^{2}} + \left[m_{H} (H, C_{i}) + \left\langle \frac{u_{fi}}{T_{d0i}^{'}} \frac{\partial H}{\partial E_{qi}^{'}} \right\rangle \right] \frac{\partial V}{\partial H} \\ + \left[m_{C} (H, C_{i}) + \left\langle \frac{u_{fi}}{T_{d0i}^{'}} \frac{\partial C}{\partial E_{qi}^{'}} \right\rangle \right] \frac{\partial V}{\partial C_{i}} \end{cases}$$

• Control constraints:
$$\left| \frac{u_{fi}}{T_{d0i}^{'}} \right| \leq K_{i}$$

> Optimal control law

$$u_{fi} = K_i T_{d0i}^{'} \operatorname{sgn}\left(\frac{\partial H}{\partial E_{qi}^{'}} \frac{\partial V}{\partial H} + \frac{\partial C_i}{\partial E_{qi}^{'}} \frac{\partial V}{\partial C_i}\right)$$



4.2 Maximizing the Security



- Case Study
 - > Results
 - Security increases









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General Forced Oscillations

- Small disturbance, linearized system
 - Condition: frequency coverage
 - Possibility: much larger

General Internal Resonant Oscillations

- Large disturbance, nonlinear system
 - Condition: frequency doubled approximately
 - Possibility: much larger





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